DIFFUSION IN A SOLID CYLINDER PART I: ADVANCING MODEL

Cho-Liang Tsai
Department of Construction Engineering, National Yunlin University of Science & Technology, Yunlin, Taiwan, R.O.C,
cclin@fcu.edu.tw

Ching-Chang Lin
Department of Civil Engineering, Feng Chia University, Taichung, Taiwan, R.O.C.

Follow this and additional works at: https://jmstt.ntou.edu.tw/journal

Part of the Engineering Commons

Recommended Citation
DOI: 10.6119/JMST-014-0117-1
Available at: https://jmstt.ntou.edu.tw/journal/vol23/iss2/1

This Research Article is brought to you for free and open access by Journal of Marine Science and Technology. It has been accepted for inclusion in Journal of Marine Science and Technology by an authorized editor of Journal of Marine Science and Technology.
DIFFUSION IN A SOLID CYLINDER PART I: ADVANCING MODEL

Acknowledgements
The authors would like to thank the National Science Council of the Republic of China, Taiwan for financially supporting this research under Contract No. (NSC97-2221-E-224- 054).
DIFFUSION IN A SOLID CYLINDER
PART I: ADVANCING MODEL

Cho-Liang Tsai\textsuperscript{1} and Ching-Chang Lin\textsuperscript{2}

\textbf{Key words:} advancing model, diffusion.

\textbf{ABSTRACT}

An advanced diffusion model is used to calculate the concentration of a substance diffused in a solid cylindrical medium. The mathematical process in this study adopts Neumann’s algorithm for applying the advancing model to revise the solution derived by Carslaw and Jaeger. The modified solution clearly indicates a diffusion front which does not exist in the original model. Calculating the diffusion depth becomes possible and is novel for a solid cylindrical medium. The major contribution of this study is the application of the advancing model to solve the diffusion problem of a cylindrical medium in cylindrical coordinate system.

\textbf{I. INTRODUCTION}

Fick’s diffusion law is widely used for studying diffusion mechanisms. The concentration of a diffusing substance in a medium depends on the location in the medium, the diffusion duration, the geometry of the medium, the environmental conditions and the material properties of both the diffusing substance and medium.

Carslaw and Jaeger (1959) applied Laplace transform to solve the temperature of a semi-infinite space in a case that the heat is conducted from the surface of the space toward its depth. By assuming the solution to be a uni-formed function, Carslaw and Jaeger formulated the solution as an asymptotic function. When the solution was applied to the diffusion problem of the same medium, which has the same governing equation as that of heat conduction problem, the solution indicated that the concentration in the medium infinitly approached zero as the diffusing substance moved along its path inward but can never be zero regardless of the duration (Crank, 1975). The solution reveals no diffusion front, and the diffusion depth is impossible to be calculated. However, transporting molecules of a diffusing substance in a medium takes time. The molecules of a diffusing substance do not appear deep inside the medium immediately after the diffusion begins. The Crank’s solution is inapplicable for diffusion in semi-infinite space in practice even if it is mathematically correct.

Carslaw and Jaeger (1959) presented Neumann’s solution for heat conduction of a semi-infinite space with a moving boundary. When the famous Neumann’s solution was applied to the diffusion in the case of a semi-infinite medium with a moving boundary, the model was called the advancing model (Crank, 1975; Chang et al., 2008; Wang, 2010; Lin et al., 2012). The solution of this model is a bi-formed and continuous but not a smooth function. The solution is in a series form in the contaminated zone which is close to the surface, while it is zero in the uncontaminated zone which is deeper than the contaminated zone. The bi-formed solution clearly indicates a diffusion front and enables calculation of the diffusion depth.

Carslaw and Jaeger (1959) also presented the solution of the temperature for heat conduction in a solid cylindrical medium in terms of the Bessel function without the advancing model. For the past half century, the high complexity of the cylindrical coordinate system has prevented researchers from deriving the solution of the temperature for heat conduction or the solution of the concentration of the diffusing substance for diffusion by using the advancing model.

This study successfully applied the Neumann’s algorithm to the cylindrical coordinate system by focusing on the local diffusion around the surface of a cylindrical medium and correlating the modification factors of the advancing model for both Cartesian and cylindrical coordinate systems. Similar to the solution with the advancing model, presented by Crank for the diffusion in a semi-infinite medium, the solution clearly shows the diffusion front. The result can be used to characterize the diffusion parameters of a cylindrical specimen medium, which is very common for concrete specimens.

\textbf{II. THEORY}

The governing equation of Fick’s second diffusion law (Crank, 1975) is
where \( c \) is the concentration of the diffusing substance in a medium defined as the mass of a diffusing substance in unit volume of medium, \( t \) is the diffusion duration, and \( D \) is the diffusivity, which is a positive constant. In a three-dimensional Cartesian coordinate system, Eq. (1) becomes

\[
\frac{\partial c}{\partial t} = D\left(\frac{\partial^2 c}{\partial x^2} + \frac{\partial^2 c}{\partial y^2} + \frac{\partial^2 c}{\partial z^2}\right)
\]

where \( x, y \) and \( z \) are the three coordinates.

In a one-dimensional case, Eq. (2) becomes

\[
\frac{\partial c}{\partial t} = D \frac{\partial^2 c}{\partial x^2}
\]

For the semi-infinite case, the medium exists only in the region where \( x \geq 0 \) and is initially free of the diffusing substance. The diffusing substance exists in the region where \( x < 0 \) and is transported inward from the surface of the medium at \( x = 0 \) according to Fick’s diffusion law (Fig. 1). In this typical one-dimensional diffusion case, \( c \) is a function of \( t \) and \( x \), represented as \( c(t, x) \). The assumed boundary condition is that, when the diffusing substance comes into contact with the medium at the boundary, the boundary is instantly saturated and remains so throughout the process of diffusion (Crank, 1975).

\[
c(t; 0) = c_\infty
\]

where \( c_\infty \) is the saturated \( c \). The initial condition is

\[
c(0, x) = 0
\]

Accordingly, \( c(t, x) \) was solved as

\[
\frac{c(t; x)}{c_\infty} = 1 - \frac{2}{\sqrt{\pi}} \sum_{n=0}^{\infty} \frac{(-1)^n}{n!} \left(\frac{x}{2\sqrt{Dt}}\right)^{2n+1}
\]

The right side of Eq. (6) has two parts, a unit constant, which is a particular solution, and a complementary function of the solution. Both parts satisfy the governing equation, Eq. (3).

Next modify Eq. (6) by dividing the complementary function by a modification factor \( C \). Eq. (6) then becomes

\[
\frac{c(t; x)}{c_\infty} = 1 - \frac{2}{\sqrt{\pi}} \sum_{n=0}^{\infty} \frac{(-1)^n}{n!} \left(\frac{x}{2\sqrt{Dt}}\right)^{2n+1}
\]

where \( C \) is a constant such that the governing equation and boundary condition are satisfied. If \( C = 1 \), Eq. (7) is identical to Eq. (6). Since \( C \) and \( c_\infty \) are constants, Eq. (7) satisfies both Eq. (3) and the boundary condition represented by Eq. (4). Neumann defined \( C \) for Eq. (7) as

\[
C = \frac{2}{\sqrt{\pi}} \sum_{n=0}^{\infty} \frac{(-1)^n}{n!} \left(\frac{\nu^{2n+1}}{n(2n+1)}\right)
\]

where \( \nu \) is Neumann’s constant named after Neumann, F. (Carslaw and Jarger, 1959; Crank, 1975; Wang et al., 2011).

Therefore, Eq. (7) becomes

\[
\frac{c(t; x)}{c_\infty} = 1 - \frac{2}{\sqrt{\pi}} \sum_{n=0}^{\infty} \frac{(-1)^n}{n!} \left(\frac{\nu^{2n+1}}{n(2n+1)}\right)
\]

\[
\sum_{n=0}^{\infty} \frac{(-1)^n}{n!} \left(\frac{\nu^{2n+1}}{n(2n+1)}\right)
\]

\[
\sum_{n=0}^{\infty} \frac{(-1)^n}{n!} \left(\frac{\nu^{2n+1}}{n(2n+1)}\right)
\]

\[
\frac{x}{2\sqrt{Dt}} = \nu \quad \text{or} \quad x = 2\nu \sqrt{Dt}
\]

and becomes negative at any location deeper than \( 2\nu \sqrt{Dt} \). A negative concentration is illogical. Redefine Eq. (10) as a bi-formed equation (Crank, 1975; Tsai et al., 2014).

\[
c(t; x) = \begin{cases} 
\sum_{n=0}^{\infty} \frac{(-1)^n}{n!} \left(\frac{\nu^{2n+1}}{n(2n+1)}\right), & 0 \leq x \leq 2\nu \sqrt{Dt} \\
0, & 2\nu \sqrt{Dt} \leq x
\end{cases}
\]
Since transport of the diffusing substance starts from \( x = 0 \), \( 2\nu \sqrt{Dt} \) stands for the diffusion depth.

For a cylindrical coordinate system, Eq. (1) becomes

\[
\frac{\partial c}{\partial t} = D \left( \frac{\partial^2 c}{\partial r^2} + \frac{1}{r} \frac{\partial c}{\partial r} + \frac{1}{r^2} \frac{\partial^2 c}{\partial \theta^2} + \frac{\partial^2 c}{\partial z^2} \right)
\]  

(12)

where \( r \) and \( \theta \) are the polar coordinates and \( z \) is the axial coordinate. In the case of axially symmetrical diffusion in an infinitely long solid cylinder with radius \( r_a \), \( c \) is dependent only on \( t \) and \( r \), \( c(t; r) \), and Eq. (12) becomes

\[
\frac{\partial c}{\partial t} = D \left( \frac{\partial^2 c}{\partial r^2} + \frac{1}{r} \frac{\partial c}{\partial r} \right)
\]  

(13)

Again, assume that the concentration of the diffusing substance in the cylinder is initially zero.

\[
c(0; r) = 0
\]  

(14)

The diffusing substance exists in the surrounding environment, penetrates the surface when the diffusion process starts and diffuses toward the center of the cylinder (Fig. 2). As in the previous case, the assumed boundary condition is that, when the diffusing substance contacts the medium at the boundary, the boundary is instantly saturated and then remains so throughout the diffusion process.

\[
c(t; r_a) = c_\infty
\]  

(15)

By separation variable, let \( c(t; r) = R(r)T(t) \) where \( R(r) \) is a function of \( r \) and where \( T(t) \) is a function of \( t \). Eq. (13) becomes

\[
R \frac{dT}{Dt} = T \left( \frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr} \right)
\]  

(16)

or

\[
\frac{dT}{dt} = \frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr}
\]  

(17)

The left side of Eq. (17) is a function of \( t \) only, and the right side is a function of \( r \) only. Both sides must be constant to be compatible in one equation. Let

\[
\frac{dT}{dt} = -k = \frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr}, \quad k : \text{constant}
\]  

(18)

when \( k = 0 \),

\[
\frac{dT}{dt} = 0
\]  

(19)

Eq. (19) implies that \( T \) is a constant, and Eq. (20) implies that \( R \) is a constant or \( ln(r) \). Since \( ln(r) \) becomes undefined when \( r = 0 \), \( ln(r) \) is an unacceptable solution for \( R \). In this particular condition, the solution of \( c(t; r) \) is a constant.

\[
c(t; r) = \beta_0, \quad \beta_0 : \text{constant}
\]  

(21)

when \( k \neq 0 \),

\[
\frac{dT}{dt} + DkT = 0
\]  

(22)

\[
\frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr} + kR = 0 \quad \text{or} \quad \frac{1}{r} \frac{d(r \frac{dR}{dr})}{dr} + kR = 0
\]  

(23)

Eq. (23) is a Bessel’s differential equation of zero order, and its solution is

\[
R(r) = J_0(\sqrt{k_m}r)
\]  

(24)

where \( m \) is a multi-value index, \( k_m \) is the multi-value \( k \), and \( J_0 \) is Bessel function of the first kind of order zero. For Eq. (22), the solution corresponding to the \( m \)-th term of \( R(r) \) is

\[
T(t) = e^{-k_mDt}
\]  

(25)

The general solution for \( c(t; r) \) is the combination of Eq. (21), Eq. (24) and Eq. (25).
\[ c(t; r) = \beta_0 + \sum_{n=1}^{\infty} [\beta_n J_0(\alpha_n) e^{-\alpha_n r / r_a}] \], \quad \beta_n : \text{constants} \quad (26)

To satisfy the boundary condition, Eq. (15), let
\[ \beta_0 = c_c, \quad k_n = \frac{(\alpha_n)^2}{r_a} \quad (27) \]
where \( \alpha_n \) is the \( m \)-th zero of \( J_0 \), listed in APPENDIX I, which is very close to \( (m - 1/4)\pi \) when \( m > 20 \) (Abramowitz and Stegun, 1972). Eq. (26) becomes
\[ c(t; r) = c_c + \sum_{n=1}^{\infty} [\beta_n J_0(\alpha_n) e^{-\alpha_n r / r_a}] \], \quad \beta_n : \text{constants} \quad (28)

The initial condition, Eq. (14), yields
\[ c_c = -\sum_{n=1}^{\infty} (\beta_n J_0(\alpha_n) e^{-\alpha_n r / r_a}) \quad (29) \]
Multiply both sides of Eq. (29) by \( r J_0(\alpha_n) r_a \), where \( n \) is an integer index, and then integrate both sides with respect to \( r \) from 0 to \( r_a \) (APPENDIX II) to obtain
\[ \beta_n = -c_c \frac{2}{\alpha_n J_1(\alpha_n)} \quad (30) \]
Eq. (26) becomes
\[ \frac{c(t; r)}{c_c} = 1 - \sum_{n=1}^{\infty} \left[ \frac{2}{\alpha_n J_1(\alpha_n)} J_0(\alpha_n) e^{-\alpha_n r / r_a} \right] \quad (31) \]
Eq. (31) is the normalized \( c(t; r) \), an uni-formed solution. The right side of Eq. (31) is separated into two parts, one part being a particular solution which is an unit constant and the other part being a complementary function. Both parts satisfy the governing equation, Eq. (13). For the case of chloride diffusion in a water-logged cylindrical concrete specimen (Wang et al., 2011), assume \( c_c = 0.025 \text{ g/cm}^3 \), \( D = 0.00758 \text{ cm}^2/\text{day} \), \( r_a = 7.5 \text{ cm} \) and the ends of the specimen are painted to block the chloride diffusion through the ends, Fig. 3(a) shows the \( c(t; r) / c_c \) versus \( r / r_a \) for different \( \sqrt{Dt} / r_a \).

After applying the Neumann’s technique to divide the complementary function by a modification factor \( C \), Eq. (31) becomes
\[ \frac{c(t; r)}{c_c} = 1 - \sum_{n=1}^{\infty} \left[ \frac{2}{\alpha_n J_1(\alpha_n)} J_0(\alpha_n) e^{-\alpha_n r / r_a} \right] \frac{1}{C} \], \quad \left\{ \begin{array}{ll}
C = 1, & r \geq r_f \\
0, & r \leq r_f 
\end{array} \right. \quad (32) \]

Since \( C \) and \( c_c \) are constants, Eq. (32) satisfies Eq. (13) and the boundary condition, Eq. (15).

When \( r \) is sufficiently small but \( t \) is not sufficiently large, the numerator of the second term on the right side of Eq. (32) could be bigger than its denominator, meaning that Eq. (32) might be negative. A negative concentration value is irrational. Eq. (32) must be set to zero under this condition. As a result, the cross section of the cylinder is separated into two zones, a contaminated zone that is closer to the surface and an uncontaminated core. However, when \( t \) is sufficiently large, the cylinder is contaminated thoroughly and there is no uncontaminated core.

Before the medium is thoroughly contaminated, \( c(t; x) \) gradually decreases as it approaches the center, becomes zero at a critical location, and is set to zero for the rest area where it is numerically negative. The critical location where \( r = r_f \) stands for the diffusion front. The zone where \( r \leq r_f \) is the uncontaminated core. The distance between the surface and diffusion front is the diffusion depth, which is not considered in Eq. (31). The location of the diffusion front \( r_f \) depends on \( t \) and can be calculated numerically by setting Eq. (32) to zero. Define the critical \( t \) when the diffusing substance reaches the center, \( t_c \). When \( t \leq t_c \), redefine Eq. (32) as

\[ \frac{c(t; r)}{c_c} = \left\{ \begin{array}{ll}
\frac{\sum_{n=1}^{\infty} \left[ \frac{2}{\alpha_n J_1(\alpha_n)} J_0(\alpha_n) e^{-\alpha_n r / r_a} \right]}{C}, & r \geq r_f \\
0, & r \leq r_f 
\end{array} \right. \quad (33) \]

Neumann defined \( C \) for Eq. (7) as Eq. (8), and resulted in the diffusion depth as \( 2\sqrt{Dt} \). Here, the important task is defining \( C \) for this cylindrical coordinate system. Before solving \( C \), however, the local diffusion near the surface should be discussed. Eq. (31) is the solution for the normalized
concentration of the cylindrical medium obtained without the advancing model. Let the original point of a unidirectional Cartesian coordinate system be placed on the left edge of the cylinder, with the x-coordinate oriented toward the center of the cylinder (Fig. 2). Clearly, \( x = r_a - r \) or \( r = r_a - x \). Eq. (31) becomes

\[
\frac{c(t; x)}{c_\infty} = 1 - \sum_{n=1}^{\infty} \left[ \frac{2}{\alpha_n J_1'(\alpha_n)} J_0(\alpha_n(1 - \frac{x}{r_a})) e^{-\frac{\alpha_n}{\sqrt{r_a}}} \right] \tag{34}
\]

When \( x \) is very small, the local geometry around the surface should be very close to a semi-infinite domain, meaning that Eq. (34) should be the same as Eq. (6).

Similarly, the complementary functions on the right side of both Eqs. (34) and (6) should be the same.

\[
\sum_{n=1}^{\infty} \left[ \frac{2}{\alpha_n J_1'(\alpha_n)} J_0(\alpha_n(1 - \frac{x}{r_a})) e^{-\frac{\alpha_n}{\sqrt{r_a}}} \right] = \frac{2}{\sqrt{\pi}} \sum_{n=0}^{\infty} (-1)^n \left( \frac{x}{2\sqrt{Dt}} \right)^{2n+1} n!(2n+1) \tag{35}
\]

When the advancing model is considered, Eq. (31) becomes Eq. (32). For the diffusion near the area close to the surface of cylinder, Eq. (32) should be very close to Eq. (9). With the aid of Eq. (35), the C in Eq. (32) is proven to be the same as that in Eq. (7) for a Cartesian coordinate system as shown in Eq. (8). Therefore, Eq. (32) becomes

\[
\frac{c(t; r)}{c_\infty} = 1 - \sum_{n=1}^{\infty} \left[ \frac{2}{\alpha_n J_1'(\alpha_n)} J_0(\alpha_n(1 - \frac{r}{r_a})) e^{-\frac{\alpha_n}{\sqrt{r_a}}} \right] \frac{1}{\sqrt{\pi}} \sum_{n=0}^{\infty} (-1)^n \left( \frac{r}{2\sqrt{Dt}} \right)^{2n+1} n!(2n+1) \tag{36}
\]

and Eq. (33) becomes

\[
\frac{c(t; r)}{c_\infty} = \begin{cases} 
1 - \sum_{n=1}^{\infty} \left[ \frac{2}{\alpha_n J_1'(\alpha_n)} J_0(\alpha_n(1 - \frac{r}{r_a})) e^{-\frac{\alpha_n}{\sqrt{r_a}}} \right] \frac{1}{\sqrt{\pi}} \sum_{n=0}^{\infty} (-1)^n \left( \frac{r}{2\sqrt{Dt}} \right)^{2n+1} n!(2n+1), & r \geq r_f \\
0, & r \leq r_f 
\end{cases} \tag{37}
\]

For the case of a waterlogged cylindrical concrete specimen with \( r_a = 7.5 \text{ cm} \), where the two ends are painted, \( c_\infty = 0.025 \text{ g/cm}^3 \) and \( D = 0.00758 \text{ cm}^2/\text{day} \). Figs. (3)-(d) show the results for \( c(t; r)/c_\infty \) versus \( r/r_a \) for varying \( \sqrt{Dt}/r_a \), \( \nu \) and \( C \), respectively.

III. DISCUSSION

Along the radius coordinate toward the center of the cylindrical medium, \( r = r_f \) is the location where \( c(t; r) \) starts to be 0, which is the location of the boundary between the
contaminated zone and the uncontaminated core. Setting the first term of the right side of Eq. (37) to zero obtains

$$\frac{2}{\sqrt{\pi}} \sum_{n=0}^{\infty} (-1)^n \frac{\nu^{2n+1}}{n!(2n+1)} = \sum_{n=1}^{\infty} \left( \frac{2}{\alpha_n J_0(\alpha_n)} \right) e^{-\left( \frac{\nu}{\alpha_n} \right)^2}$$  \hspace{0.5cm} (38)

The relationship between $r_f/r_a$ and $\sqrt{\Delta r/\nu}$ can be calculated numerically via Eq. (38) for different $\nu$ (Fig. 4).

Clearly, $r_f = r_a - 2\nu \sqrt{\Delta r}$ around the surface of the cylindrical medium where $2\nu \sqrt{\Delta r}$ is the diffusion depth for a semi-infinite medium. In the cylindrical medium, the speed of the diffusion front increases as it approaches the center. This phenomenon does not occur in a semi-infinite medium. When the diffusing substance approaches the center of the medium, it is thickened because of the smaller space. Fick’s first law is that the diffusion rate of a diffusing substance, along a diffusion path, is proportional to the derivative of the concentration of the diffusing substance. When the substance thickens along its path inward toward the center, the derivative of the concentration increases, and the diffusion rate accelerates. Such an inward flow accelerated by the thickening diffusion substance which is named thickening-substance-accelerated-inward flow, TSAI flow in short, will be critical for further studies of reverse osmosis efficiency.

The area deeper than $r_f$ is the uncontaminated zone, where $c(t,r)$ is zero. When $r_f = 0$, the $t_c$ is defined as the critical duration when the diffusion reaches the center of the medium and Eq. (38) becomes

$$\frac{2}{\sqrt{\pi}} \sum_{n=0}^{\infty} (-1)^n \frac{\nu^{2n+1}}{n!(2n+1)} = \sum_{n=1}^{\infty} \left( \frac{2}{\alpha_n J_1(\alpha_n)} \right) e^{-\left( \frac{\nu}{\alpha_n} \right)^2}$$  \hspace{0.5cm} (39)

The relationship between $\sqrt{\Delta r/\nu}$ and $\nu$ can be calculated numerically via Eq. (39) (Fig. 5). When $t \leq t_c$, Eq. (37) is applied to get the concentration of the diffusing substance. When $t \geq t_c$, Eq. (36) is applied because there is no uncontaminated core. Future studies can extend Eqs. (36) and (37) to a cylindrical specimen with finite length, which is very common for concrete specimens.

Values of $r_f$ and $t_c$ depend on $t$, $\nu$, $D$, and $r_a$, and must be calculated numerically from Eqs. (38) and (39). The process is tedious and needs further study for simplification, which will be included in the future work.

Cylindrical specimens are commonly used in compression test to determine the strength of concrete. If the specimen is placed in an environment full of chloride or other diffusing substance before the compression test, the concentration of chloride in the specimen can be measured by using the broken specimen after the compression test. Strength and chloride concentration can be obtained from the same specimen. By fitting the result of this work to the data of chloride concentration in the cylindrical concrete specimens, the parameters of chloride diffusion in the concrete will be obtained as well as its strength. In addition, the results can also be used to study the influence of chloride concentration on the concrete strength, and this should be another interesting work for the future.

IV. APPENDIX

1. Appendix I: Zeros of $J_0$

<table>
<thead>
<tr>
<th>$m$</th>
<th>$\alpha_m$</th>
<th>$m$</th>
<th>$\alpha_m$</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>2.4048255604</td>
<td>51</td>
<td>159.4366111649</td>
</tr>
<tr>
<td>2</td>
<td>5.5200781056</td>
<td>52</td>
<td>162.5781886695</td>
</tr>
<tr>
<td>3</td>
<td>8.6537279135</td>
<td>53</td>
<td>165.7197667486</td>
</tr>
<tr>
<td>4</td>
<td>11.7915344396</td>
<td>54</td>
<td>168.8613453698</td>
</tr>
<tr>
<td>5</td>
<td>14.9309177091</td>
<td>55</td>
<td>172.0029245037</td>
</tr>
<tr>
<td>6</td>
<td>18.0710639685</td>
<td>56</td>
<td>175.1445041225</td>
</tr>
</tbody>
</table>
### Appendix II: Verification of Eq. (30)

Multiply both sides of Eq. (29) by \( r J_0(\alpha m r_{\alpha} / r_a) \), where \( n \) is an integer index, and integrate both sides with respect to \( r \) from 0 to \( r_a \). The left side becomes

\[
\int_0^{r_a} c_o r J_0(\alpha m r_{\alpha} / r_a) dr = c_o \int_0^{r_a} r [1 - r_a^2 / 2^2 (1!)^2 + r_a^4 / 2^4 (2!)^2 - r_a^6 / 2^6 (3!)^2 + \ldots] dr
\]

The right side becomes

\[
-\sum_{m=1}^{\infty} (\beta_m J_m(\alpha m r_{\alpha} / r_a) J_0(\alpha m r_{\alpha} / r_a) dr)
\]

Since \( J_0(\alpha m r_{\alpha} / r_a) \) is one of the solutions of Eq. (23),

\[
\frac{dJ_0(\alpha m r_{\alpha} / r_a)}{dr} + \frac{\alpha m r_{\alpha}}{2} J_0(\alpha m r_{\alpha} / r_a) = 0
\]

or

\[
J_0(\alpha m r_{\alpha} / r_a) = -\left(\frac{r_a}{\alpha m}\right)^{\frac{1}{2}} \frac{d}{dr} \left[ \frac{dJ_0(\alpha m r_{\alpha} / r_a)}{dr} \right]
\]

The right side becomes

\[
\int_0^{r_a} J_0(\alpha m r_{\alpha} / r_a) r J_0(\alpha m r_{\alpha} / r_a) dr \text{ in Eq. (A2) becomes}
\]

\[
\int_0^{r_a} J_0(\alpha m r_{\alpha} / r_a) r J_0(\alpha m r_{\alpha} / r_a) dr = -\int_0^{r_a} J_0(\alpha m r_{\alpha} / r_a) r (\frac{r_a}{\alpha m})^{\frac{1}{2}} \frac{d}{dr} \left(\frac{r_a}{r_{\alpha}}\right) d\left(\frac{r_a}{r_{\alpha}}\right)
\]

\[
= -\left(\frac{r_a}{\alpha m}\right)^{\frac{1}{2}} \int_0^{r_a} J_0(\alpha m r_{\alpha} / r_a) dr \left[\frac{d}{dr} \left(\frac{r_a}{r_{\alpha}}\right)\right] d\left(\frac{r_a}{r_{\alpha}}\right)
\]

#### 2. Appendix II: Verification of Eq. (30)

Multiply both sides of Eq. (29) by \( r J_0(\alpha m r_{\alpha} / r_a) \), where \( n \) is an integer index, and integrate both sides with respect to \( r \) from 0 to \( r_a \). The left side becomes
\[-\left(\frac{r_a}{\alpha_n}\right)^2 \int_0^\infty \frac{dJ_0(\alpha_n \frac{r}{r_a})}{r} dr \right]\]

By the same process,

\[\int_0^\infty r J_0(\alpha_n \frac{r}{r_a})r J_0(\alpha_n \frac{r}{r_a}) dr = \left(\frac{r_a}{\alpha_n}\right)^2 \int_0^\infty \frac{dJ_0(\alpha_n \frac{r}{r_a})}{r} \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} dr \]  

(A5)

\[= \left(\frac{r_a}{\alpha_n}\right)^2 \int_0^\infty r \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} dr \]  

(A6)

By the same process,

\[\int_0^\infty J_0(\alpha_n \frac{r}{r_a}) r J_0(\alpha_n \frac{r}{r_a}) dr = \int_0^\infty J_0(\alpha_n \frac{r}{r_a}) r J_0(\alpha_n \frac{r}{r_a}) dr \]  

(A7)

Eq. (A5) and Eq. (A6) are the same. Subtract Eq. (A5) by Eq. (A6) to obtain

\[0 = \left(\frac{1}{\alpha_n^2} - \frac{1}{\alpha_m^2}\right) \int_0^\infty r \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} \frac{dJ_0(\alpha_m \frac{r}{r_a})}{dr} dr \]  

(A8)

On the right side of Eq. (A8), either \(m = n\) will make the first term zero, or the integration should be zero. Eq. (A8) verifies the orthogonality of Bessel function, meaning that the integration in Eq. (A2) must vanish when \(m \neq n\). Eq. (A2) becomes

\[-\beta_s \int_0^\infty \frac{r J_0^2(\alpha_n \frac{r}{r_a})}{dr} dr \]  

(A9)

Multiply both sides of Eq. (A4) by \(2r \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr}\). The left side becomes

\[\frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} J_0(\alpha_n \frac{r}{r_a}) = \frac{dJ_0^2(\alpha_n \frac{r}{r_a})}{dr} \]  

(A10)

The right side becomes

\[-\left(\frac{r_a}{\alpha_n}\right)^2 \frac{1}{2} \left(\frac{r}{r_a}\right)^2 \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} \]  

(A11)

Combine Eq. (A10) and Eq. (A11) to obtain

\[-\left(\frac{r_a}{\alpha_n}\right)^2 \frac{1}{r} \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} \]  

(A12)

or

\[-\left(\frac{r_a}{\alpha_n}\right)^2 \frac{dJ_0^2(\alpha_n \frac{r}{r_a})}{dr} = r^2 \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} \]  

(A13)

Integrate both sides of Eq. (A13) with respect to \(r\) from 0 to \(r_a\).

\[\int_0^{r_a} \frac{dJ_0^2(\alpha_n \frac{r}{r_a})}{dr} dr = \int_0^{r_a} r \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} dr = \beta_s \frac{1}{\alpha_n^2} \int_0^{r_a} \frac{r J_0^2(\alpha_n \frac{r}{r_a})}{dr} dr \]  

(A14)

Eq. (A9) and Eq. (A2) become

\[-\beta_s \int_0^\infty \frac{r J_0^2(\alpha_n \frac{r}{r_a})}{dr} dr = -\beta_s \frac{1}{2} \left(\frac{r_a}{\alpha_n}\right)^2 \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} \frac{dJ_0(\alpha_n \frac{r}{r_a})}{dr} \]  

(A15)

Combine Eq. (A1) and Eq. (A15) to obtain

\[\beta_s = c_n \frac{2}{\alpha_n J_1(\alpha_n)} \]  

(A16)
or

\[ \beta_n = -c_n \frac{2}{\alpha_n J_1(\alpha_n)} \quad (A17) \]

ACKNOWLEDGMENTS

The authors would like to thank the National Science Council of the Republic of China, Taiwan for financially supporting this research under Contract No. (NSC97-2221-E-224-054).

REFERENCES


